

HW6-4 Soln)

This isn't as bad as the previous example. The force of the hand is always in the direction of motion of the ball.

$$W_{\text{TOTAL}} = \Delta K + \Delta U$$

$$W_{\text{Hand}} = \int F \cos\theta \, dl = F \cos\theta \int dl = F \cos\theta l = F \cos\theta \pi r = 30(\cos(0))\pi(0.6) = 56.5 \text{ J} .$$

W_g = conservative

Then,

$$W_{NC} = \Delta K + \Delta U$$

$$W_{\text{Hand}} = \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2 + gmy_f - gmy_i$$

Set lowest point as $y=0$

$$y_i = 2r = 1.2 \text{ m}$$

$$W_{\text{Hand}} = \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2 - gmy_i$$

$$v_f = \sqrt{\frac{2(W_{\text{Hand}} + \frac{1}{2}mv_i^2 + gmy_i)}{m}} = \sqrt{\frac{2(56.5 + \frac{1}{2}0.35(12^2) + 10(0.35)1.2)}{0.35}} = 22.2 \text{ m/s}$$