

$$\begin{aligned} \text{a}_\text{g} &= 9.8 \text{ m/s}^2 \text{ (or } 10 \text{ m/s}^2) \\ \text{g} &= 9.8 \text{ N/kg} \end{aligned}$$

$$\sin\theta=\frac{opp}{hyp}\quad\cos\theta=\frac{adj}{hyp}\quad\tan\theta=\frac{opp}{adj}$$

$$a^2+b^2=c^2$$

$$ax^2+bx+c=0\quad x=\frac{-b\pm\sqrt{b^2-4ac}}{2a}$$

$$A_x = A \cos \theta_A \quad A_y = A \sin \theta_A$$

$$A=\sqrt{A_x^2+A_y^2}\quad \theta_A=\arctan\frac{A_y}{A_x}*{}$$

$$\vec{A}\cdot\vec{B}=A_xB_x+A_yB_y+A_zB_z=AB\cos\theta_{A,B}$$

$$|\vec{A}\times\vec{B}|=AB\sin\theta_{A,B}(RHR)$$

$$\begin{matrix} i & j & k & i & j \\ \vec{A}\times\vec{B} = A_x & A_y & A_z & A_x & A_y \\ B_x & B_y & B_z & B_x & B_y \end{matrix}$$

$$\Delta x=x_f-x_i$$

$$v_{xAVE}=\frac{\Delta x}{\Delta t}\quad v_x=\lim\nolimits_{x\rightarrow 0}\frac{\Delta x}{\Delta t}=\frac{dx}{dt}$$

$$a_{xAVE}=\frac{\Delta v_x}{\Delta t}\quad a_x=\lim\nolimits_{x\rightarrow 0}\frac{\Delta v_x}{\Delta t}=\frac{dv_x}{dt}$$

$$v_x=v_{xi}+a_xt\quad v_{xAVE}=\frac{v_x+v_{xi}}{2}$$

$$x=x_i+v_{xi}t+\tfrac{1}{2}a_xt^2\quad v_x^2=v_{xi}^2+2a_x(x-x_i)$$

$$R=\frac{v_o^2\sin(2\theta_o)}{|a_g|}ORR=\frac{v_o^2\sin(2\theta_o)}{g}$$

$$\sum_n\;\vec F_n=m\vec a$$

$$\vec F_{A,B}=-\vec F_{B,A}$$

$$F_{fK}=\mu_K F_N$$

$$F_{fs}\leq \mu_S F_N$$

$$a_C=\frac{v_T^2}{r}=\omega^2 r$$

$$s=r\theta$$

$$v_T=r\omega$$

$$\omega=\frac{d\theta}{dt}$$

$$W_{TOTAL}=\Delta K$$

$$W_{NC}=\Delta K+\Delta U$$

$$W=F\Delta x \cos\theta_{F,\Delta x}\quad W=\int \vec{F}(\vec{r})\cdot d\vec{r}$$

$$F_x=-\frac{dU}{dx}\quad \vec{F}=-\frac{\partial U}{\partial x}\hat{i}-\frac{\partial U}{\partial y}\hat{j}-\frac{\partial U}{\partial z}\hat{k}$$

$$K=\tfrac{1}{2}mv^2\quad U_g=gmy\quad U_{sp}=\tfrac{1}{2}kx^2\quad \Delta U=-W_{CONS}$$

$$F_{SP}=(-)kx$$

$$P=\frac{\delta W}{dt}$$

$$\vec{J}=\vec{F}\Delta t=\Delta\vec{p}\quad \vec{J}=\int \vec{F}(t)dt=\Delta\vec{p}\quad \vec{p}=m\vec{v}$$

$$v_{1f}=\frac{m_1-m_2}{m_1+m_2}v_{1i}\quad v_{2f}=\frac{2m_1}{m_1+m_2}v_{1i}$$

$$s=r\theta\quad v_T=r\omega\quad a_T=r\alpha$$

$$\omega_{AVE}=\frac{\theta_f-\theta_i}{t_f-t_i}\quad \vec{\omega}=\frac{d\vec{\theta}}{dt}$$

$$\alpha_{AVE}=\frac{\omega_f-\omega_i}{t_f-t_i}\quad \vec{\alpha}=\frac{d\vec{\omega}}{dt}$$

$$\omega=\omega_i+\alpha t\quad \omega_{AVE}=\frac{\omega+\omega_i}{2}$$

$$\theta=\theta_i+\omega_it+\tfrac{1}{2}\alpha t^2\quad \omega^2=\omega_i^2+2\alpha(\theta-\theta_i)$$

$$\tau = F_{\perp} r = lF = F \sin \theta_{r,F} (RHR) \quad \vec{\tau} = \vec{r} \times \vec{F}$$

$$\sum_n \vec{\tau}_n = I \vec{\alpha} \quad I = \sum_n m_n r_n^2 \quad I = \int dm r^2$$

$$x_{CM} = \frac{\sum_n m_n x_n}{\sum_n m_n} \quad x_{CM} = \frac{\int dm x}{\int dm} \quad \text{Similarly for } y \text{ and } z$$

$$I_{POINTMASS} = MR^2 \quad I_{HOOP} = MR^2$$

$$I_{DISK/CYLINDER} = \frac{1}{2} MR^2 \quad I_{SOLIDSPHERE} = \frac{2}{5} MR^2 \quad I_{THINROD} = \frac{1}{12} ML^2$$

$$K_{ROT} = \frac{1}{2} I \omega^2 \quad \vec{L} = I \vec{\omega} = \vec{r} \times \vec{p} \quad \vec{\tau} = \frac{d\vec{L}}{dt}$$

$$\nu = \lambda f \quad f = \frac{1}{P}$$

$$\nu = \sqrt{\frac{T}{\mu}} \quad \nu = \sqrt{\frac{B}{\rho}} \quad \nu = \sqrt{\frac{Y}{\rho}} \quad Z = \sqrt{Y\rho} \quad Z = \sqrt{T\mu}$$

$$k_{EFF} = k_1 + k_2 + \dots \quad (\text{side by side}) \quad \frac{1}{k_{EFF}} = \frac{1}{k_1} + \frac{1}{k_2} + \dots \quad (\text{end 2 end})$$

$$\nu(T) = (331 \text{m/s}) \sqrt{1 + \frac{T}{273}}$$

$$I = \frac{\text{Power}}{\text{Area}} \quad dB = 10 \log \frac{I}{I_0} \quad I_0 = 10^{-12} W/m^2$$

$$f_n = \frac{n\nu}{2L} ; n = 1, 2, 3, \dots \quad f_n = \frac{n\nu}{4L} ; n = 1, 3, 5, \dots$$

$$P = 2\pi \sqrt{\frac{M}{K}} \quad P = 2\pi \sqrt{\frac{L}{g}}$$

$$\sin\theta \approx \theta_{radians}$$

$$f_{heard} = f_{emitted} \frac{\nu_{sound} \pm \nu_{observer}}{\nu_{sound} \mp \nu_{source}}$$

$$f_{heard} = \frac{f_1 + f_2}{2} \quad f_{beat} = |f_1 - f_2|$$

